

# Calculus of Variations

## Summer Term 2017

### Lecture 5

Universität des Saarlandes

05 May 2017

## Purpose of Lesson:

- To consider Dido's problem.
- To discuss the catenary problem.

## A simplified form of Dido's problem:

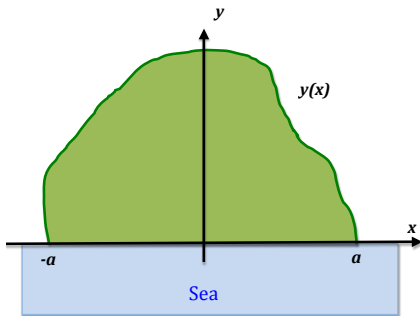
$$J[y] = \int_{-a}^a y dx \rightarrow \max$$

subject to

$$G[y] = \int_{-a}^a \sqrt{1 + (y')^2} dx = L$$

and

$$y(-a) = y(a) = 0$$



For simplicity take

$$2a < L \leq \pi a$$

# Approach

As before

- we perturb the curve, and consider the first variation
- but we cannot perturb by an arbitrary function  $\varepsilon\eta$ . because then the constraint

$$\mathcal{G}[y + \varepsilon\eta] = L$$

might be violated.

- **solution:** use the same approach as in constrained maximization, e.g. use **Lagrange multipliers**

## Problem

To find the minimum (or maximum) of  $f(x)$  for  $x \in \mathbb{R}^n$  subject the constraints

$$g_i(x) = 0, \quad i = 1, \dots, m < n \quad (5.1)$$

- Solution requires **Lagrange Multipliers**.
- Minimize (ot maximize) a new function (of  $m + n$  variables)

$$h(x, \lambda) = f(x) + \sum_{i=1}^m \lambda_i g_i(x),$$

where  $\lambda_i$  are the undetermined Lagrange multipliers.

- The constants  $\lambda_1, \dots, \lambda_m$  are evaluated by means of the set of equations consisting of (5.1) and

$$\frac{\partial h(x, \lambda)}{\partial x_j} = 0, \quad j = 1, \dots, n$$

# Why Lagrange multipliers?

- Maximize  $f(x)$  subject to  $g(x) = 0$

$$h(x) = f(x) + \lambda g(x).$$

So  $\frac{\partial h}{\partial x_i} = 0$  implies  $\frac{\partial f}{\partial x_i} = -\lambda \frac{\partial g}{\partial x_i}$ .

- Assume  $x$  is an extremum which satisfies the constraint, and consider all of the  $x + \Delta x$  in the neighborhood of  $x$  that also satisfy the constraint (i.e.  $g(x + \Delta x) = g(x) = 0$ ).
- We also know from Taylor's theorem that

$$g(x + \Delta x) = g(x) + \nabla g(x) \cdot \Delta x + O(\Delta x^2)$$

which implies that for small  $\Delta x$

$$\nabla g(x) \cdot \Delta x = 0.$$

- If we take  $\frac{\partial f}{\partial x_j} = -\lambda \frac{\partial g}{\partial x_j}$  then  $\nabla f \cdot \Delta x = 0$ .

# Lagrange multipliers in functionals

To maximize

$$J[y] = \int_a^b F(x, y, y') dx$$

subject to

$$\mathcal{G}[y] = \int_a^b G(x, y, y') dx = L$$

we instead consider the problem of finding extremals of

$$\mathcal{H}[y] = \int_a^b H(x, y, y') dx = \int_a^b \{F(x, y, y') + \lambda G(x, y, y')\} dx$$

# The Euler-Lagrange equations

The Euler-Lagrange equations become

$$\frac{\partial H}{\partial y} - \frac{d}{dx} \left( \frac{\partial H}{\partial y'} \right) = 0$$

where  $H = F + \lambda G$ , and  $\lambda$  is the unknown Lagrange multiplier.



## Example 5.1 (Simple Dido's problem)

$$\mathcal{H}[y] = \int_{-a}^a \left( y + \lambda \sqrt{1 + (y')^2} \right) dx$$

so

$$\frac{\partial H}{\partial y} = 1$$

$$\frac{d}{dx} \left( \frac{\partial H}{\partial y'} \right) = \frac{d}{dx} \left( \frac{\lambda y'}{\sqrt{1 + (y')^2}} \right)$$

and the Euler-Lagrange equation is

$$\frac{d}{dx} \frac{\lambda y'}{\sqrt{1 + (y')^2}} = 1$$

### Example 5.1 (Simple Dido's problem)

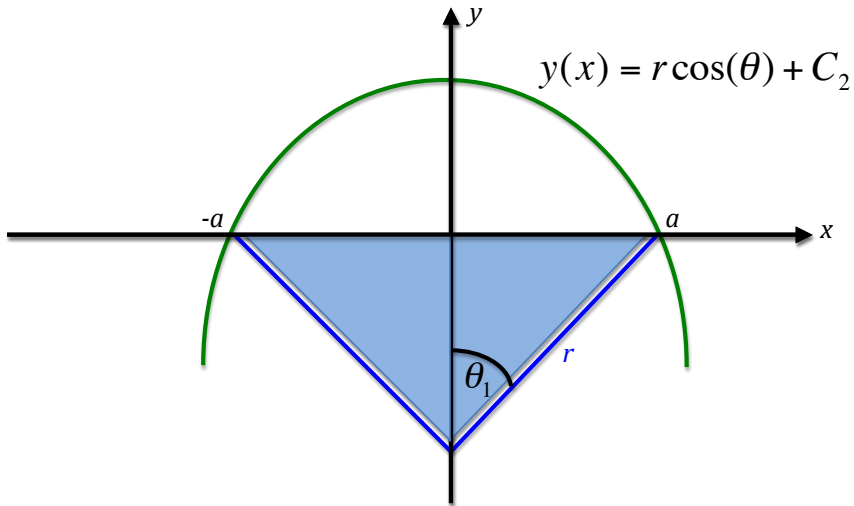
- Integrating with respect to  $x$  we get

$$\begin{aligned}x + C_1 &= \lambda \sin(\theta) \\ y &= -\lambda \cos(\theta) + C_2\end{aligned}$$

where  $\lambda$ ,  $C_1$  and  $C_2$  are determined by the two end-points, and the length of the curve  $L$ .

- We may draw a sketch of the solution, and clearly we can identify  $-\lambda = r$  the radius of a circle, of which our region is a segment.
- Note we deliberately started with

$$2a < L \leq \pi a.$$



### Example 5.1 (Simple Dido's problem)

- We can see that the arc length of the enclosing curve will be

$$L = 2\theta_1 r$$

and the the value on the right-end determines that

$$r = \frac{a}{\sin(\theta_1)}$$

- Therefore, we have

$$L = \frac{2a\theta_1}{\sin(\theta_1)}$$

from which we may determine  $\theta_1$ .

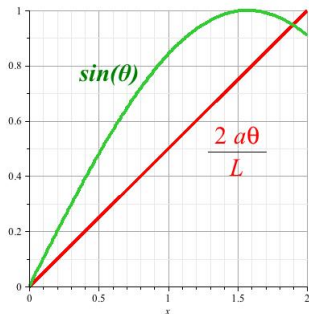
## Example 5.1 (Simple Dido's problem)

- Since we determine  $\theta_1$  from

$$\sin(\theta_1) = \frac{2a}{L}\theta_1$$

we may compute

$$r = \frac{a}{\sin(\theta_1)}.$$



## Example 5.1 (Simple Dido's problem)

- From the conditions  $y(\pm a) = 0$  it follows that

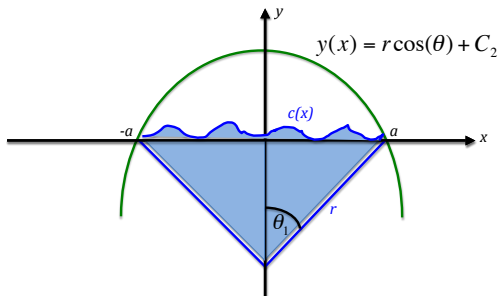
$$C_2 = -a \cot(\theta_1).$$

- The maximum possible area bounded by a curve of fixed length is a circle. So the city of Carthage is circular in shape.
- The story of Carthage isn't quite true (see picture below).



## What effect would a realistic coastline have?

- Coast  $c(x)$ .



- Area =  $\int_{-a}^a (y - c) dx$
- Note that  $c$  doesn't depend on  $y$  or  $y'$ , so the Euler-Lagrange equations are unchanged, provided  $c(x) < y(x)$  for the extremal.

## What effect would a realistic coastline have?

- If the condition  $c(x) < y(x)$  is not satisfied then the area integral includes negative components, so the problem we are maximizing is not really Dido's problem any more (she can't own negative areas).
- We really want to maximize

$$\text{Area} = \int_a^b [y - c]^+ dx$$

where

$$[x]^+ = \begin{cases} x, & \text{for } x > 0 \\ 0, & \text{otherwise} \end{cases}$$

- Note that the function  $[x]^+$  does not have a derivative at  $x = 0$ .



## Example 5.2 (Catenary of fixed length)



Picture: A hanging chain forms a catenary

- What happens to the shape of the suspended wire when we fix the length of the wire?

## Example 5.2 (Catenary of fixed length)

- As before we seek a minimum for the potential energy

$$J[y] = \int_{x_0}^{x_1} y \sqrt{1 + (y')^2} dx \rightarrow \min$$

but now we include the constraint that the length of the wire is  $L$ , e.g.

$$G[y] = \int_{x_0}^{x_1} \sqrt{1 + (y')^2} dx = L$$

- We seek extremals of the new functional

$$\mathcal{H}[y] = \int_{x_0}^{x_1} (y + \lambda) \sqrt{1 + (y')^2} dx.$$

- Notice that  $H(x, y, y') = (y + \lambda) \sqrt{1 + (y')^2}$  has no explicit dependence on  $x$ , and so we may compute

$$H - y'H_{y'} = \frac{(y + \lambda)(y')^2}{\sqrt{1 + (y')^2}} - (y + \lambda) \sqrt{1 + (y')^2} = \text{const}$$

- Perform the change of variables  $u = y + \lambda$ , and note that  $u' = y'$  so that the above can be rewritten as

$$\frac{u(u')^2}{\sqrt{1 + (u')^2}} - u \sqrt{1 + (u')^2} = C_1. \quad (5.2)$$

- It is easy to see that Eq. (5.2) reduces to

$$\frac{u^2}{1 + (u')^2} = C_1^2. \quad (5.3)$$

- Eq. (5.3) is exactly the same equation (in  $u$ ) as we had previously for the catenary in  $y$ . So, the result is a catenary also, but shifted up or down by an amount such that the length of the wire is  $L$ .

$$y = u - \lambda = C_1 \cosh\left(\frac{x - C_2}{C_1}\right) - \lambda$$

- So, we have three constants to determine
  - 1 we have two end points
  - 2 we have the length constraint

- We put  $C_2 = 0$  and consider the even solution with  $x_0 = -1$ ,  $y(x_0) = 1$ ,  $x_1 = 1$  and  $y(1) = 1$ .



$$\begin{aligned} L &= \int_{-1}^1 \sqrt{1 + (y')^2} dx = \int_{-1}^1 \cosh\left(\frac{x}{C_1}\right) dx \\ &= C_1 \left[ \sinh\left(\frac{x}{C_1}\right) \right]_{-1}^1 = 2C_1 \sinh\left(\frac{1}{C_1}\right) \end{aligned}$$

- Now we can calculate  $C_1$  from the above equality.
- Once we know  $C_1$  we can calculate  $\lambda$  to satisfy the end heights  $y(-1) = y(1) = 1$ .

- Thus, we know that a solution of the catenary problem with length constraint has the form

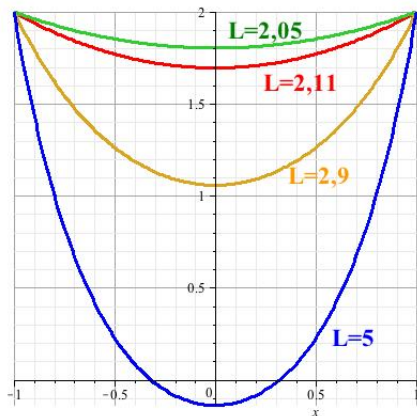
$$y = C \cosh\left(\frac{x}{C}\right) - \lambda,$$

and  $y$  satisfy the additional conditions

$$y(-1) = y(1) = 2, \quad L = \int_{-1}^1 \sqrt{1 + (y')^2} dx = 2C \sinh\left(\frac{1}{C}\right).$$

- Using Maple we calculate  $y$  for the natural catenary (without length constraint), as well as for  $L = 2.05$ ,  $L = 2.9$  and  $L = 5$ . See Worksheet 1 for the detailed calculation.

- All catenaries are valid, but one is **natural**



- The red curve shows the natural catenary (without length constraint), and the green, yellow and blue curves show other catenaries with different lengths.

# Pathologies

Note that in both cases ("simple Dido's problem" and "catenary of fixed length")

- the approach only works for certain ranges of  $L$ .
- If  $L$  is too small, there is no physically possible solution
  - e.g., if wire length  $L < x_1 - x_0$
  - e.g., if oxhide length  $L < x_1 - x_0$
- If  $L$  is too large in comparison to  $y_1 = y(x_1)$ , the solution may have our wire dragging on the ground.